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# SCHWARZ METHOD FOR VARIATIONAL INEQUALITIES 

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#### Abstract

In this paper we want to bring into question the Schwarz overlapping domain decomposition method, taking into account that domain decomposition is a technique where the original domain is decomposed into a set of smaller sub- domains. We will talk about the additive Schwarz method for variational inequalities, presenting first the general framework where we expose the problem that we want to study. The purpose of this work s is to exploit a convergence theory for the specified method. The convergence results from the norm estimates for some error reduction operators. The additive Schwarz algorithm is formulated in a way which admits a nice recurrence for the errors between two consecutive steps. Through a study for projection operators onto closed and convex subsets of a Hilbert space, we will demonstrate a geometric convergence for our method. We have to mention that for simplicity, the theory will be demonstrated only for the obstacle problem.


Keywords: domain decomposition, admissible decomposition, error estimates

## 1. Introduction

The additive Schwarz method, named after H. A. Schwarz, solves a boundary value problem for a partial differential equation approximately by splitting it into boundary value problems on smaller domains and adding the results.
The paper is organized as follows: firstly we will study the variational inequalities in an abstract framework, then the general result developed before will be applied to an obstacle problem in Sobolev spaces.

## 2. The Schwarz method for variational inequalities

2.1. General framework An iterative scheme

Let $(V,(\cdot)$,$) be a Hilbert space and$ $a: V \times V \rightarrow \mathbf{R} \quad$ a bilinear, symmetric, coercive and continuous form and $K \subset V$ a convex, closed subset. We consider the following variational inequality:

where $f$ is a linear continuous functional on $V$ (i.e. $f \in V^{\prime \prime}$ ).
From the properties of the bilinear form $a(6,)^{2}$ it results that $a(u, v) \cong(u, v), \forall u, v \in V$.
Furthermore, we have
$a(u, v)=(u, v), \forall u, v \in V$. Let be $F: V \rightarrow \mathbf{R}$.

It is known that the problem ( P 1 ) is equivalent to the following minimization

(P2)
We want to approximate the solution of (P1) by iterative procedures. Then, let $V_{i}$, $t=\sqrt{1, \%}$ be subspaces of $V$ such that $V=\sum_{i=1}^{m} V_{i}$

The interest is to define an algorithm for constructing a sequence $\left(u_{n}\right)_{n \in s}$ to approximate the exact solution of the problem ( P 1 ), which is the minimum of the functional $F$. It is natural to impose that the solution from the step $n+1$ to decrease the value of the functional $F$, i.e. $F\left(u_{n+1}\right) \leq F\left(u_{n}\right)$.
Algorithm description
We proceed in two steps.

1. It is defined $u_{n, t} \in V_{i}$ such that:

$$
\begin{equation*}
E\left(u_{n}+u_{n, t}\right) \leftrightarrows E\left(u_{n}+v_{i}\right) \quad \forall v_{i} \in K_{n, i} \tag{P3}
\end{equation*}
$$

where $\tilde{K}_{n, t}=\left\{v_{i} \in V_{i} u_{n}+v_{t} \in E\right\}$.
2. It is defined
$u_{n+1}=u_{n}+\rho \sum_{i=1}^{m} u_{n, i}$,
with $\rho$ chosen such that $u_{n+1} \in K$.
Let be $k=\rho m \leq 1$. We have:
$u_{n+1}=u_{n}+\rho \sum_{i=1}^{m} u_{n, i}=\left(1-\mu u_{n}+\beta \sum_{i=1}^{m} \frac{1}{m}\left(u_{n}+u_{n, i}\right)\right.$
Since $u_{n} \in K$ and $\sum_{i=1}^{m} \frac{1}{m}\left(u_{n}+u_{n i t}\right)$ e $K$, we observe that a sufficient condition to have $u_{n+1} \in K$ is that $a \leq 1$, i.e. $\rho \leq \frac{1}{m}$.
Obviously, the formulation of the problem (P3) is equivalent to the following variational inequality:
$\left\{u_{n, i} \in K_{n, t}\right.$

$$
\begin{equation*}
a\left(u_{n}+u_{n, i} v_{i}-u_{n, i}\right) \geq f\left(v_{i}-u_{n, i}\right) \quad \vee v_{i} \in K_{n, i} \tag{P4}
\end{equation*}
$$

Furthermore, we will make the following assumption which is necessary to demonstrate the convergence:

Assumption 2.1.
The problem (P4) is equivalent to the following problem:

```
\(\left\{\begin{array}{l}u_{\pi, \ell} \mathbf{G} K_{6, \ell} \\ a\left(u_{n}+u_{m, i v} v_{i}-u_{n, i}\right) \approx a\left(u_{,} v_{i}-u_{m, i}\right) \forall v_{i} \in K_{n, i}\end{array}\right.\) (P5)
```

We can write the problem (P5) under the form:
$\left\{\begin{array}{l}u_{n, i} \in R_{n, i} \\ a\left(u_{n, i}, v_{i}-u_{n, i}\right) w_{2}\left(u-u_{n}, v_{i}-u_{n, i}\right) \forall v_{i} \in K_{n, i}\end{array}\right.$
The correction is given by the solving the problem (P6).

Let $P_{n, t}: V_{t} \rightarrow K_{n, t}$ be the projection operator on the convex closed set $K_{n, \zeta}$. From (P6) it results that:
$u_{n, i}=P_{n, i}\left(u-u_{n}\right)$
With these preliminary the iterative scheme is defined as follows:

## Algorithm 2.1.

Let be $u_{0} \in K$. We compute the sequence of approximations $\left\{w_{\downarrow}{ }^{n \tau}\right.$ as follows:

1. We compute $u_{n, i}$ from the problem (P4).
2. We compute $u_{n+1}$ from (*).
3. Let $e_{n}=u-u_{n}$ be the error at the step $n$.

From (**) it results that:
$u_{n, t}=P_{n, t} e_{n}$.
Thus, from (*) it results that:
$e_{n+1}=\left(l-\rho I_{n}^{\prime}\right) e_{n}$,
where $T_{n}$ is the additive operator
$T_{n}=\sum_{i=1}^{m} P_{n, i}$.
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To demonstrate the convergence of the Schwarz method, we analyse the additive operator $T_{n}$.

### 2.2. Technical estimates

Let $K_{i} \subset V_{x} t=\overline{\mathbf{1}, m}$ be convex closed subsets such that $0 \in K_{i}, \mathbf{V} i=\overline{1, m}$. We observe that this hypothesis is satisfied for $K_{i}=K_{\pi, t}$ because $u_{n} \in K$. Let be $f \in V$.
We consider the problem (P1) in the case $a(\cdot)=,(\cdot \cdot)$, which is equivalent to $u=P_{l} f$, where $F_{i}: V \rightarrow K_{i}$ is the projection operator, or we can have:

$$
\begin{align*}
& \left\{\begin{array}{l}
P_{i} f \in K_{t} \\
\left.v P_{i f} f, v-P_{i} f\right) \geq\left(f, v-P_{i} f\right)
\end{array}\right. \\
& v v \in K_{i} . \tag{2.1}
\end{align*}
$$

The corresponding additive operator is given by:

$$
\begin{equation*}
T=\sum_{i=1}^{m} P_{i} \tag{A}
\end{equation*}
$$

Taking $v=0$ in (2.1) we obtain:

Next, we investigate the boundedness of the operator $T$. Let be $\mathcal{C}_{i j} \in[0,1]$ which satisfies the inequality:
$\left|\left\{P_{i t}, f_{r} P_{i}\right)\right| \leq c_{i t}\left\|P_{t} f\right\|\left\|P_{i g}\right\|$, $\forall f, z \in V$
Let be $C=\left(C_{t!}\right)_{t, j=1, m}$ and let $|C|$ be the norm of the matrix C .

$$
\begin{gather*}
\left\|P_{i} f\right\|^{2}=\left(P_{i} f, P_{i} f\right) \leftrightarrows\left(f, P_{i} f\right) \\
\forall f \in V . \tag{2.2}
\end{gather*}
$$

From (2.1) we obtain:
$\left(f, v-P_{i} f\right) \leq \mathbb{Z}\left(P_{\imath} f, v, v \in K_{i}\right.$, (2.3)

Definition 2.1: A vector $f \mathbf{e} V$ is said to have an admissible decomposition with respect to $\left\{K_{1}\right\}$ and a fixed constant $C_{0}$, if there exists a partition of $f$ :
$f=f_{2}+f_{z}+\cdots+f_{m} f_{i} \leq K_{l}$,
such that
$\sum_{i=1}^{m}\|f\|^{2} \Phi C_{0}\|f\|^{2}$.
Lemma 2.1: If $w \in V$ has an admissible decomposition with respect to $\left\{K_{4} t\right\}$ and the constant $C_{0}$, then we have the inequality: $(f, f) s\left(2+C_{n}\right)(f, T f)$.
Demonstration: We have:

## $\|C\|\|f\|^{\text {. }}$

(B)
and

$$
\begin{equation*}
\left(2+c_{0}\right)^{-2}\|f\|^{2} 5\left\|c^{\prime} f\right\|^{2} s \tag{C}
\end{equation*}
$$

$|C|^{2}\|f\|^{2}$.
Demonstration: For (B) we have:

- from lemma 2.1 we have:
$(f, f) \Phi\left(2+c_{0}\right)(f, T f) \Rightarrow \quad\left(2+c_{0}\right)^{-1}$
$\| f \mathbf{I}^{2}=(f, T f) \geq f \in V$.
- 

$(f, T f)\|\|\|\| f f(\|s\|\| \|\| \|\|f\|=\mid C\| \| f \|, v f \in V$
, where we used (2.6).
For (C) we have:

- from lemma 2.1 and the Cauchy- Schwarz inequality we have
$\|f\|^{2} \leq\left(2+C_{0}\right)(f, T f) \leftrightarrows\left(2+C_{0}\right)\|f\|\|T f\| \Rightarrow$ $\left(2+C_{0}\right)^{-2}\|f\|^{2} \leq \quad\|T f\|^{2} \forall f \in V$.
- from lemma 2.2, the relation (2.6), we have:
$\|T f\|^{2} \leq|C|^{2}\|f\|^{2} \forall f \in V$.


### 2.3. The convergence

Theorem 2.2: Let $u_{n}$ be the solution given by algorithm 2.1 and let $u$ be the solution of the problem ( P 1 ). We assume that the assumption 2.1 is satisfied. We also assume that $w_{0} \mathbf{e} \boldsymbol{K}$ is an element such that at each step $n, u-$ $u_{n}$ has an admissible decomposition with respect to $\left.\mathbb{[ \{ K} K_{n, n}^{*}\right\}$ and a fixed constant $C_{0}$ independent of $n$. Then, for $\rho$ chosen sufficiently small, $\exists \theta \in(0,1)$ such that:
$\left\|u-u_{n+1}\right\|^{2} \pi^{2}\left\|u-u_{n}\right\|^{2}$.
Demonstration: We know that

$$
e_{n-1}=\left(I-\rho T_{r}\right) e_{n}
$$

It results that:

$$
\left\|e_{n+1}\right\|^{2}=\left\|e_{n}\right\|^{2}-2 \rho\left(T_{n} e_{n}, e_{n}\right)+\rho^{2}\left\|_{n} e_{n}\right\|^{2}
$$

We use the relation (B) from theorem 2.1, i.e.: $\left(2+C_{0}\right)^{-1}\|f\|^{\mathbf{5}} \boldsymbol{\Psi}(f, T f)$,
stating that in our case we have
$\left(2+C_{0}\right)^{-1}\left\|e_{n}\right\|^{2} \leq\left(e_{n}, T_{n} e_{n}\right)$.
So, $-\left(T_{n} e_{n} e_{n}\right) \leq-\left(2+C_{0}\right)^{-1}\left\|e_{n}\right\|^{2}$.
We also use the relation (C) from theorem 2.1. i.e.:
stating that in our case we have
$\left\|T_{n} e_{n}\right\|^{2} \leq|C|^{2}\left\|e_{n}\right\|^{2}$.
Replacing these two obtained relations in the above equality, we have:
$\left\|e_{n+1}\right\|^{2} \leq\left[1-2 \rho\left(z+C_{0}\right)^{1}+\rho^{2} \mid C \|^{2}\right]\left\|e_{n}\right\|^{2}$ , (D)
where $C$ depends on $n$ and $C_{l}^{n} \in[0,1]$ such that:
$\left(P_{n, f} f, P_{n, f} g\right) \subseteq C_{n}\left\|P_{n, f} f\right\| P_{n, f} g \| \vee f, g \in V$

### 3.4. An application in the domain decomposition method

For simplicity, the idea will be illustrated only for obstacle problems. Let $\Omega \in \mathbf{R}^{n}, n \in \mathbf{N}$, be an open bounded domain with Lipschitz continuous boundary $\Gamma^{\prime}=\partial \Omega$. We assume that $\partial \Omega=\Gamma_{1} \cup \Gamma_{\mathbf{2}}, \Gamma_{1} \cap \Gamma_{2}=\emptyset$, is a partition of the boundary such that meas $\left(\Gamma_{t} 1\right)>0$. We consider the Sobolev space
$V=\left\{v \in H^{\top} 1(\Omega): v=0\right.$ on $[\Gamma \rrbracket \pm 1\}$,
the convex set
$K=\{v \in V: v \geq 0$ in $\Omega$,
and the problem:
$\left\{\begin{array}{l}u \in K \\ a(u, v-u) \geq f(v-w) \quad \forall v \in K,\end{array}\right.$
where $a(\cdot)$ is a symmetric, continuous and positive definite bilinear form on $V \times V$ and $f \in V^{\prime}, V^{\prime}$ being the dual of the space $V$. For simplicity, the analysis can be restricted to the following bilinear form model:
$a(v, w)=\int_{\Omega}$
$v_{i} W \in V$.
First, we decompose the domain into overlapping sub-domains:
$\|T f\|^{2}{ }^{\leftrightarrows}|C|^{2}\|f\|^{2}$,
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（2．10）
where $\Omega_{i}$ are open sub－domains with Lipschitz continuous boundary．
Secondly，we define $V_{1} t=\left\{v_{1} t \in V: v_{1} t=0\right.$ in $\Omega-\Omega_{1}^{-} \ell, t=(1, m)^{-}$．Next，we apply the abstract theory that we exposed it before，to approximate the solution $u$ of the problem （2．8）．
Algorithm 2．2：Let be $u_{0} \mathbf{e} K$ ．We compute the sequence of approximations $\left\{u_{4} n\right\}$ as follows：
1．We assume that $u_{n}$ is known．We consider the convex set：
$K_{n, i}=\left\{v_{i} \in V_{i} v_{i}+u_{n} \in K_{i n}\right.$
For each $t \Sigma\left\{1, \ldots, m n_{i}^{2}\right.$ ，we compute $v_{n, i}$ by solving the problem：

$$
\left\{\begin{array}{l}
v_{n, t} \in K_{\pi, i}  \tag{2.12}\\
\quad a\left(u_{n}+v_{n, k} v-v_{n, t}\right) \geq f\left(v-v_{n, i}\right) \quad \forall v \in K_{n, i}
\end{array}\right.
$$

We update the approximation by：
$u_{n+1}=u_{n}+\mu \sum_{i=1}^{m} w_{n, i}$,
where $\rho$ should be chosen such that $u_{n+1} \in K$ ．
The following lemma provides a useful criterion for choosing $\rho$ ．
Lemma 2．3：For any $x \in \Omega$ ，let $N(x)$ be the number of sub－domains containing $x$ ．If $p$ is chosen as a smooth positive function such that：
$\rho(x) N(x) \leq 1, \forall x \in \Omega$,
then the approximation $u_{n+1}$ from（2．13）is a function in the convex set $K$ ．Also，the convergence that results theorem 2.2 holds in this case if：

$$
1-2 \rho_{1}\left(1-\zeta_{0}\right)^{-1}+\rho_{2}^{2}|C|^{2} \leq \theta<1,
$$

where $\rho_{1} \min _{\rho \in, x)}$ and $\rho_{2}=\max _{\rho \in x, 9}$
Demonstration：First，for any $x \in \Omega$ ， $\Sigma(l=1)^{1} m \llbracket \llbracket v_{1}(n, l)(x) \geq \rrbracket N(x) \min n_{\uparrow} \llbracket v_{1}(n, t) \rrbracket(x)$ ．

So，from（2．13）and（2．14），we have：

$$
u_{n+1}(x) \geq u_{n}(x)+\rho(x) N(x) \min _{v_{n, p}(x)}
$$

If $m \ln -1 \llbracket v_{1}\left(n_{1} t\right) 】(x) \geq 0$ ，then from the above inequality we have that $w_{n+1}(x) \geq 0$ ．
If $m i n-1 \llbracket v_{1}(n, t) 】(x)<0$ ，then from （2．14）we have：
$u_{1}(n+1)(x) \geq u_{1} n(x)+\min \operatorname{Ti}^{i} \llbracket v_{1}(n, t) 】(x) \geq 0$, where at the last step we have used the fact that：$u_{n}(x)+v_{s, i}(x) \geq \mathbb{Q}_{v} \mathbf{x} t \in\left\{1_{p} \ldots, m_{t}^{2}\right.$ ．
Regarding the second part of the lemma，we see that it results from the relation：

$$
\left\|e_{n+1}\right\|^{2} S\left(1-2 \rho_{1}\left(1-C_{0}\right)^{-1}+\rho_{2}^{2}|C|^{2}\right)\left\|e_{n}\right\| \|^{2}
$$ ，instead of（D）．

To demonstrate the convergence by using the abstract result established above，we first have to show that the assumption 2.1 is satisfied for the model problem（2．8）．
With $u_{n, i}=u_{n}+v_{n, i}$ ，we can rewrite the problem（P5）as follows：
团 $u_{n, t} \in K_{n, t}+u_{n}$

$$
\begin{aligned}
& a\left(u_{n, \delta}, v_{\varepsilon}-u_{n, \delta}\right) \geq a\left(u_{1} v_{i}-u_{n, \delta}\right) \quad \mathbf{~} \quad(2.15) \\
& +v_{\varepsilon} \in K_{n, \delta} .
\end{aligned}
$$

Then，the assumption 2.1 is equivalent to the equivalence of the problems（2．12）and（2．15）．

Lemma 2.4: Let $u$ be the solution of the problem (2.8) and $u_{n, i}$ the solution of the problem (2.15). Then, we have the statements:

1. If the approximation from the step $n$ satisfies the conditions $u_{n} \in E$ and $u-u_{n} \in K$, then $u_{m, i} \in K$ and $u-u_{x, l} \in K$.
2. If the inequalities (2.12) and (2.15) are equivalent in the sense that:
$\left\{\begin{array}{c}u_{n, i} \text { verifies (2.15) } \\ v_{n, i} \text { verifies (2.12), }\end{array}\right.$
then $u_{n, i}=u_{n}+v_{n, t}$.
Demonstration: 1. Let be $\Omega_{1} t^{7}+=\{x \in$ $S_{1} t\left\lfloor u \rrbracket_{1}(n, t)>0\right.$ 〕.
Taking $v_{i}=u_{n, i} \pm e W_{i}$ in (2.15) we have:
$a\left(a_{n, i}-u_{i} s w_{i}\right)=0, \forall W_{i} \in V_{i} W_{i}=0$
$\Omega-\Omega_{i}^{*}$.
Since $s \in(0,1)$, it results that:

$$
\begin{align*}
& a\left(u_{n, i}-u_{i} w_{i}\right)=0_{z} \forall w_{i} \in V_{i} w_{i}=0 \text { on } \\
& \Omega-\Omega_{i} . \tag{2.16}
\end{align*}
$$

2.We show that $u-u_{n, t} \in K$. Let be $D_{t}=\left\{x \in E ; u_{n, t}-u>0\right\}$.
We claim that $D_{i} \simeq \Omega_{i}^{\ell}$.
In fact, if $x \in D_{i}$, then $u_{m, i}(x)-u(x)>0$,i.e. $\left.u_{n, t}(x)>u_{x} x\right) \geq 0$.
Since in $\Omega-\Omega_{i}$ we have $u_{n, i}=u_{n} \varsigma u$, then (2.17) involves $x \in \Omega_{i}$ and $u_{n, i}(x) \geq 0$. Thus, $x \in \Omega \frac{+}{?}$. We observe that $u-u_{n} \in K$ (i.e. $\left.u_{n} \leq u\right)$ and therefore,
$u_{n, i}-u=u_{n}-u \leq 0$ on $\partial \Omega_{i} \cap \Omega$.
Since $D_{i} \subset \Omega_{i}^{*}$, the function
$\Phi_{i}= \begin{cases}u_{n, i}(x)-u(x), x \in D_{i} \\ 0 & , x \in \Omega-D_{\ell},\end{cases}$
is defined on $V_{i}$ and vanishes in $\Omega-\bar{\Omega}_{i}$.
Replacing $w_{i}$ in (2.16) by $\phi_{i}$ we have:
$a\left(u_{m, i}-u_{r} \Phi_{i}\right)=0 \Rightarrow \quad a\left(\Phi_{i}, \Phi_{i}\right)=0 \Rightarrow$ $F_{i}=0$.

Therefore, $D_{i}$ must be the empty set. This shows that $u-u_{n, i} \geq 0$ and thus, $u-u_{i, i} \in K$.
We show now that the inequalities (2.15) and (2.12) are equivalent in the sense established in the theorem.
In fact, from (2.15) we have:
$a\left(u_{n, i}, v_{i}-u_{n, i}\right) \geq a\left(u_{,} v_{i}\right)-a\left(u_{r} u_{n, i}\right)$,
$\forall v_{i} \in K_{n, i}+u_{n}=K$.
It is known that $a\left(u, v_{i}\right)$ e $f\left(v_{i}\right), v i=\overline{1, m}$ and since ${ }^{u-u_{n, t} \in K}$, we have:
$-a\left(u, u_{m, i}\right)=a\left(u, u-u_{m, i}-u\right) \geq f\left(u-u_{m, i}-u\right)=f\left(-u_{m, i}\right)$.
Replacing the last two relations in (2.18), we obtain:
$a\left(u_{n, i}, v_{i}-u_{n, i}\right) \geq f\left(v_{i}-u_{n, i}\right), v_{i} \in u_{n}+K_{R, i}$.
Taking $v_{n, i}=u_{n, i}-u_{n}$, we observe that $v_{n, i}$ provides a solution of the problem (2.12). This, together with the uniqueness of the solutions of the problems (2.15) and (2.12), goes to the wanted equivalence. By computing, we have:
$a\left(u_{n}+v_{n, i} v_{i}-v_{n, i}\right)-a\left(u_{n}+v_{R, i} u_{n}\right) \geq f\left(v_{i}-v_{n, i}\right)-f\left(u_{n}\right)$
From the demonstration of lemma 2.3 it results that the new approximation $u_{n+1}$ lies in $K$ as long as $u_{n} \in K$ and $\rho(x) N(x) \leq 1$. We assume that $u-u_{n} \in K$. We want to know if $u-u_{n+1} \in K$ is valid under the same constraint of $\tilde{F}$. The answer is positive. To see why this holds, we observe that from (2.13) we have:
$u-u_{n+1}=u-u_{n}-\rho \sum_{i=1}^{m} v_{n, i}$.
We observe that from lemma 2.4 we have:
$u_{n}+v_{n, i}=u_{n, i} \leq u \Rightarrow v_{n, i} \leq u-u_{n}$.
Therefore,
$\sum_{i=1}^{m} v_{n, i}(x) 5 N(x)\left(x(x)-u_{n}(x)\right)$.
It results that
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$$
\left.u-u_{n}-\rho \sum_{i=1}^{m} v_{n, z} \geq u-u_{n}-\rho N i x u_{n}-u_{n}\right)=\left(1-\rho M h_{n}-u_{n}\right) \geq 0
$$

$$
\text { Thus, } n-u_{n+1} \in K
$$

The result can be summarized as follows:
Theorem 2.3: Let $u$ be the solution of the inequality (2.8) and let $\left\{u_{4} n\right\}$ be a sequence of approximations given by the algorithm 2.2 , in which the parameter $P$ is chosen according to the lemma 2.3. If the initial guess $u_{0}$ is selected such that $u_{0}$, $u-u_{0} \in K$, then $u_{n+1}, u-u_{n+1} \in K$. Furthermore, the problem (2.12) is equivalent (2.15) in the sense that $u_{n, i}=u_{n}+u_{n, i}$.

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